The high-level error bound for shifted surface spline interpolation

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Radial function interpolation of scattered data is a frequently used method for multivariate data fitting. One of the most frequently used radial functions is called shifted surface spline, introduced by Dyn, Levin and Rippa in [4] for R^2 . Then it's extended to R^n for $n \geq 1$. Many articles have studied its properties, as can be seen in [2, 3, 5, 15, 16, 18, 19, 20, 21]. When dealing with this function, the most commonly used error bounds are the one raised by Wu and Schaback in [17], and the one raised by Madych and Nelson in [13]. Both are $O(d^l)$ as $d \to 0$, where l is a positive integer and d is the fill-distance. In this paper we present an improved error bound which is $O(\omega^{1/d})$ as $d \to 0$, where $0 < \omega < 1$ is a constant which can be accurately calculated. **Keywords**:radial basis function, shifted surface spline, error bound.

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1 Introduction

Let h be a continuous function on R^n which is conditionally positive definite of order m. Given data (x_j, f_j) , j = 1, ..., N, where $X = \{x_1, ..., x_N\}$ is a

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subset of points in \mathbb{R}^n and the $f'_j s$ are real or complex numbers, the so-called h spline interpolant of these data is the function s defined by

$$s(x) = p(x) + \sum_{j=1}^{N} c_j h(x - x_j), \tag{1}$$

where p(x) is a polynomial in P_{m-1} and $c'_i s$ are chosen so that

$$\sum_{j=1}^{N} c_j q(x_j) = 0 (2)$$

for all polynomials q in P_{m-1} and

$$p(x_i) + \sum_{j=1}^{N} c_j h(x_i - x_j) = f_i, \ i = 1, \dots, N.$$
(3)

Here P_{m-1} denotes the class of those polynomials of \mathbb{R}^n of degree $\leq m-1$.

It is well known that the system of equations (2) and (3) has a unique solution when X is a determining set for P_{m-1} and h is strictly conditionally positive definite. For more details please see [12]. Thus, in this case, the interpolant s(x) is well defined.

We remind the reader that X is said to be a determining set for P_{m-1} if p is in P_{m-1} and p vanishes on X imply that p is identically zero.

In this paper h is defined by formula

$$h(x) := (-1)^m (|x|^2 + c^2)^{\frac{\lambda}{2}} \log(|x|^2 + c^2)^{\frac{1}{2}}, \ \lambda \in Z_+, \ m = 1 + \frac{\lambda}{2}, \ c > 0,$$
$$x \in \mathbb{R}^n, \ \lambda, \ n \ even, \tag{4}$$

where |x| is the Euclidean norm of x, and λ , c are constants. In fact, the definition of shifted surface spline covers odd dimensions. For odd dimensions, it's of the form

$$h(x) := (-1)^{\lceil \lambda - \frac{n}{2} \rceil} (|x|^2 + c^2)^{\lambda - \frac{n}{2}}, \ n \ odd, \ \lambda \in Z_+ = \{1, 2, 3, \ldots\}$$

$$and \ \lambda > \frac{n}{2}.$$
(5)

However, this is just multiquadric whose exponential error estimates have already been constructed by Madych and Nelson in [14], and the calculation of the constant ω in $O(\omega^{\frac{1}{d}})$ can be found in [11].Hence we will not discuss it. Instead, we will focus on even dimensions.

1.1 A Bound for Multivariate Polynomials

A key ingredient in the development of our estimates is the following lemma which gives a bound on the size of a polynomial on a cube in \mathbb{R}^n in terms of its values on a discrete subset which is scattered in a sufficiently uniform manner. We cite it directly from [14] and omit its proof.

Lemma 1.1 For n = 1, 2, ..., define γ_n by the formulae $\gamma_1 = 2$ and, if n > 1, $\gamma_n = 2n(1 + \gamma_{n-1})$. Let Q be a cube in R^n that is subdivided into q^n identical subcubes. Let Y be a set of q^n points obtained by selecting a point from each of those subcubes. If $q \ge \gamma_n(k+1)$, then for all p in P_k

$$sup_{x \in Q}|p(x)| \le e^{2n\gamma_n(k+1)} sup_{y \in Y}|p(y)|.$$

1.2 A Variational Framework for Interpolation

The precise statement of our estimates concerning h splines requires a certain amount of technical notation and terminology which is identical to that used in [13]. For the convenience of the reader we recall several basic notions.

The space of complex-valued functions on \mathbb{R}^n that are compactly supported and infinitely differentiable is denoted by \mathcal{D} . The Fourier transform of a function ϕ in \mathcal{D} is

$$\hat{\phi}(\xi) = \int e^{-i\langle x,\xi\rangle} \phi(x) dx.$$

A continuous function h is conditionally positive definite of order m if

$$\int h(x)\phi(x) * \tilde{\phi}(x)dx \ge 0$$

holds whenever $\phi = p(D)\psi$ with ψ in \mathcal{D} and p(D) a linear homogeneous constant coefficient differential operator of order m. Here $\tilde{\phi} = \overline{\phi(-x)}$ and * denotes the convolution product

$$\phi_1 * \phi_2(t) = \int \phi_1(x)\phi_2(t-x)dx.$$

As pointed out in [13], this definition of conditional positive definiteness is equivalent to that of [12] which is generally used.

If h is a continuous conditionally positive definite function of order m, the Fourier transform of h uniquely determines a positive Borel measure μ on $\mathbb{R}^n \setminus \{0\}$ and constants a_{γ} , $|\gamma| = 2m$ as follows: For all $\psi \in \mathcal{D}$

$$\int h(x)\psi(x)dx = \int \{\hat{\psi}(\xi) - \hat{\chi}(\xi) \sum_{|\gamma| < 2m} D^{\gamma} \hat{\psi}(0) \frac{\xi^{\gamma}}{\gamma!} \} d\mu(\xi) + \sum_{|\gamma| \le 2m} D^{\gamma} \hat{\psi}(0) \frac{a_{\gamma}}{\gamma!}, \tag{6}$$

where for every choice of complex numbers c_{α} , $|\alpha| = m$,

$$\sum_{|\alpha|=m} \sum_{|\beta|=m} a_{\alpha+\beta} c_{\alpha} \overline{c_{\beta}} \ge 0.$$

Here χ is a function in \mathcal{D} such that $1 - \hat{\chi}(\xi)$ has a zero of order 2m + 1 at $\xi = 0$; both of the integrals $\int_{0 < |\xi| < 1} |\xi|^{2m} d\mu(\xi)$, $\int_{|\xi| \ge 1} d\mu(\xi)$ are finite. The choice of χ affects the value of the coefficients a_{γ} for $|\gamma| < 2m$.

Our variational framework for interpolation is supplied by a space we denote by $C_{h,m}$. If

$$\mathcal{D}_m = \{ \phi \in \mathcal{D} : \int x^{\alpha} \phi(x) dx = 0 \text{ for all } |\alpha| < m \},$$

then $\mathcal{C}_{h,m}$ is the class of those continuous functions f which satisfy

$$\left| \int f(x)\phi(x)dx \right| \le c(f) \left\{ \int h(x-y)\phi(x)\overline{\phi(y)}dxdy \right\}^{\frac{1}{2}}$$
 (7)

for some constant c(f) and all ϕ in \mathcal{D}_m . If $f \in \mathcal{C}_{h,m}$, let $||f||_h$ denote the smallest constant c(f) for which (7) is true. Recall that ||f|| is a semi-norm and $\mathcal{C}_{h,m}$ is a semi-Hilbert space; in the case m = 0 it is a norm and a Hilbert space respectively.

2 Main Results

We first recall that the function h defined in (4) is conditionally positive definite of order $m = 1 + \frac{\lambda}{2}$. This can be found in [5] and many relevant papers. Its Fourier transform [6] is

$$\hat{h}(\theta) = l(\lambda, n)|\theta|^{-\lambda - n} \tilde{\mathcal{K}}_{\frac{n+\lambda}{2}}(c|\theta|)$$
(8)

where $l(\lambda, n) > 0$ is a constant depending on λ and n, and $\tilde{\mathcal{K}}_{\nu}(t) = t^{\nu} \mathcal{K}_{\nu}(t)$, $\mathcal{K}_{\nu}(t)$ being the modified Bessel function of the second kind[1]. Then we have the following lemma.

Lemma 2.1 Let h be as in (4) and m be its order of conditional positive definiteness. There exists a positive constant ρ such that

$$\int_{\mathbb{R}^n} |\xi|^k d\mu(\xi) \le l(\lambda, n) \cdot \sqrt{\frac{\pi}{2}} \cdot n \cdot \alpha_n \cdot c^{\lambda - k} \cdot \Delta_0 \cdot \rho^k \cdot k! \tag{9}$$

for all integer $k \geq 2m + 2$ where μ is defined in (6), α_n denotes the volume of the unit ball in \mathbb{R}^n , c is as in (4), and Δ_0 is a positive constant.

Proof. We first transform the integral of the left-hand side of the inequality into a simpler form.

$$\begin{split} &\int_{R^n} |\xi|^k d\mu(\xi) \\ &= \int_{R^n} |\xi|^k l(\lambda,n) \tilde{\mathcal{K}}_{\frac{n+\lambda}{2}}(c|\xi|) |\xi|^{-\lambda-n} d\xi \\ &= l(\lambda,n) c^{\frac{n+\lambda}{2}} \int_{R^n} |\xi|^{k-\frac{n+\lambda}{2}} \cdot \mathcal{K}_{\frac{n+\lambda}{2}}(c|\xi|) d\xi \\ &\sim l(\lambda,n) c^{\frac{n+\lambda}{2}} \sqrt{\frac{\pi}{2}} \int_{R^n} |\xi|^{k-\frac{n+\lambda}{2}} \cdot \frac{1}{\sqrt{c|\xi|} \cdot e^{c|\xi|}} d\xi \\ &= l(\lambda,n) c^{\frac{n+\lambda}{2}} \cdot \sqrt{\frac{\pi}{2}} \cdot n \cdot \alpha_n \int_0^\infty r^{k-\frac{n+\lambda}{2}} \cdot \frac{r^{n-1}}{\sqrt{cr} \cdot e^{cr}} dr \\ &= l(\lambda,n) c^{\frac{n+\lambda}{2}} \sqrt{\frac{\pi}{2}} \cdot n \cdot \alpha_n \cdot \frac{1}{\sqrt{c}} \int_0^\infty \frac{r^{k+\frac{n-\lambda-3}{2}}}{e^{cr}} dr \\ &= l(\lambda,n) c^{\frac{n+\lambda}{2}} \sqrt{\frac{\pi}{2}} \cdot n \cdot \alpha_n \cdot \frac{1}{\sqrt{c}} \cdot \frac{1}{c^{k+\frac{n-\lambda-1}{2}}} \int_0^\infty \frac{r^{k+\frac{n-\lambda-3}{2}}}{e^r} dr \\ &= l(\lambda,n) \sqrt{\frac{\pi}{2}} \cdot n \cdot \alpha_n \cdot c^{\lambda-k} \int_0^\infty \frac{r^{k'}}{e^r} dr \ where \ k' = k + \frac{n-\lambda-3}{2}. \end{split}$$

Note that $k \geq 2m + 2 = 4 + \lambda$ implies $k' \geq \frac{n + \lambda + 5}{2} > 0$.

Now we divide the proof into three cases. Let $k'' = \lceil k' \rceil$ which is the smallest integer greater than or equal to k'.

Case 1. Assume k'' > k. Let k'' = k + s. Then

$$\int_0^\infty \frac{r^{k'}}{e^r} dr \le \int_0^\infty \frac{r^{k''}}{e^r} dr = k''! = (k+s)(k+s-1)\cdots(k+1)k!$$

and

$$\int_0^\infty \frac{r^{k'+1}}{e^r} dr \le \int_0^\infty \frac{r^{k''+1}}{e^r} dr = (k''+1)! = (k+s+1)(k+s)\cdots(k+2)(k+1)k!.$$

Note that

$$\frac{(k+s+1)(k+s)\cdots(k+2)}{(k+s)(k+s-1)\cdots(k+1)} = \frac{k+s+1}{k+1}.$$

The condition $k \geq 2m + 2$ implies that

$$\frac{k+s+1}{k+1} \le \frac{2m+3+s}{2m+3} = 1 + \frac{s}{2m+3}.$$

Let $\rho = 1 + \frac{s}{2m+3}$. Then

$$\int_0^\infty \frac{r^{k''+1}}{e^r} dr \le \Delta_0 \cdot \rho^{k+1} \cdot (k+1)!$$

if $\int_0^\infty \frac{r^{k''}}{e^r} dr \le \Delta_0 \cdot \rho^k \cdot k!$. The smallest k'' is $k_0'' = 2m + 2 + s$ when k = 2m + 2. Now,

$$\int_0^\infty \frac{r^{k_0''}}{e^r} dr = k_0''! = (2m+2+s)(2m+1+s)\cdots(2m+3)(2m+2)!$$

$$= \frac{(2m+2+s)(2m+1+s)\cdots(2m+3)}{\rho^{2m+2}} \cdot \rho^{2m+2} \cdot (2m+2)!$$

$$= \Delta_0 \cdot \rho^{2m+2} \cdot (2m+2)!$$

$$where \Delta_0 = \frac{(2m+2+s)(2m+1+s)\cdots(2m+3)}{\rho^{2m+2}}.$$

It follows that $\int_0^\infty \frac{r^{k'}}{e^r} dr \leq \Delta_0 \cdot \rho^k \cdot k!$ for all $k \geq 2m + 2$. Case2. Assume k'' < k. Let k'' = k - s where s > 0. Then

$$\int_0^\infty \frac{r^{k'}}{e^r} dr \le \int_0^\infty \frac{r^{k''}}{e^r} dr = k''! = (k-s)! = \frac{1}{k(k-1)\cdots(k-s+1)} \cdot k!$$

and

$$\int_0^\infty \frac{r^{k'+1}}{e^r} dr \le \int_0^\infty \frac{r^{k''+1}}{e^r} dr$$

$$= (k''+1)! = (k-s+1)! = \frac{1}{(k+1)k\cdots(k-s+2)} \cdot (k+1)!.$$

Note that

$$\left\{ \frac{1}{(k+1)k\cdots(k-s+2)} / \frac{1}{k(k-1)\cdots(k-s+1)} \right\} \\
= \frac{k(k-1)\cdots(k-s+1)}{(k+1)k\cdots(k-s+2)} \\
= \frac{(k-s+1)}{k+1} \\
\le 1.$$

Let $\rho = 1$. Then

$$\int_0^\infty \frac{r^{k''+1}}{e^r} dr \le \Delta_0 \cdot \rho^{k+1} \cdot (k+1)!$$

if $\int_0^\infty \frac{r^{k''}}{e^r} dr \le \Delta_0 \cdot \rho^k \cdot k!$. The smallest k is $k_0 = 2m + 2$. Hence the smallest k'' is $k_0'' = k_0 - s = 2m + 2 - s$. Now,

$$\int_0^\infty \frac{r^{k_0''}}{e^r} dr = k_0''! = (2m+2-s)! = (k_0-s)!$$

$$= \frac{1}{k_0(k_0-1)\cdots(k_0-s+1)} \cdot (k_0!)$$

$$= \Delta_0 \cdot \rho^{k_0} \cdot k_0! \text{ where } \Delta_0 = \frac{1}{(2m+2)(2m+1)\cdots(2m-s+3)}.$$

It follows that $\int_0^\infty \frac{r^{k'}}{e^r} dr \leq \Delta_0 \cdot \rho^k \cdot k!$ for all $k \geq 2m + 2$. Case 3. Assume k'' = k. Then

$$\int_0^\infty \frac{r^{k'}}{e^r} dr \le \int_0^\infty \frac{r^{k''}}{e^r} dr = k! \quad and \quad \int_0^\infty \frac{r^{k'+1}}{e^r} dr \le (k+1)!.$$

Let $\rho = 1$. Then $\int_0^\infty \frac{r^{k'}}{e^r} dr \leq \Delta_0 \cdot \rho^k \cdot k!$ for all k where $\Delta_0 = 1$. The lemma is now an immediate result of the three cases.

Remark: For the convenience of the reader we should express the constants Δ_0 and ρ in a clear form. It's easily shown that

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- (a)k'' > k if and only if $n \lambda > 3$,
- (b)k'' < k if and only if $n \lambda \le 1$, and
- (c)k'' = k if and only if $1 < n \lambda \le 3$,

where k'' and k are as in the proof of the lemma. We thus have the following

situations.

(a)
$$n - \lambda > 3$$
. Let $s = \lceil \frac{n - \lambda - 3}{2} \rceil$. Then

$$\rho = 1 + \frac{s}{2m+3}$$
 and $\Delta_0 = \frac{(2m+2+s)(2m+1+s)\cdots(2m+3)}{\rho^{2m+2}}$.

(b)
$$n - \lambda \le 1$$
. Let $s = -\lceil \frac{n - \lambda - 3}{2} \rceil$. Then

$$\rho = 1 \text{ and } \Delta_0 = \frac{1}{(2m+2)(2m+1)\cdots(2m-s+3)}.$$

(c) $1 < n - \lambda \le 3$. We have

$$\rho = 1$$
 and $\Delta_0 = 1$.

Before introducing our main theorem, we need the following two lemmas, first of which is cited directly from [14].

Lemma 2.2 Let Q, Y, and γ_n be as in Lemma 1.1. Then, given a point x in Q, there is a measure σ supported on Y such that

$$\int_{\mathbb{R}^n} p(y)d\sigma(y) = p(x)$$

for all p in P_k , and

$$\int_{R^n} d|\sigma|(y) \le e^{2n\gamma_n(k+1)}.$$

Lemma 2.3 For any positive integer k,

$$\frac{\sqrt{(2k)!}}{k!} \le 2^k.$$

Proof. This inequality holds for k = 1 obviously. We proceed by induction.

$$\frac{\sqrt{[2(k+1)]!}}{(k+1)!} = \frac{\sqrt{(2k+2)!}}{k!(k+1)} = \frac{\sqrt{(2k)!}}{k!} \cdot \frac{\sqrt{(2k+2)(2k+1)}}{k+1} \\
\leq \frac{\sqrt{(2k)!}}{k!} \cdot \frac{\sqrt{(2k+2)^2}}{k+1} \leq 2^k \cdot \frac{(2k+2)}{k+1} = 2^{k+1}.$$

Because of the local nature of the result, we first restrict our attention to the case where x lies in a cube.

Theorem 2.4 Suppose h is defined as in (4). Let μ be its corresponding measure as in (6). Then, given a positive number b_0 , there are positive constants δ_0 and ω , $0 < \omega < 1$, which depend on b_0 for which the following is true:

If $f \in \mathcal{C}_{h,m}$ and s is the h spline that interpolates f on a subset X of \mathbb{R}^n , then

$$|f(x) - s(x)| \le \sqrt{l(\lambda, n)} \cdot \left(\frac{\pi}{2}\right)^{1/4} \cdot \sqrt{n \cdot \alpha_n} \cdot c^{\frac{\lambda}{2}} \cdot \sqrt{\Delta_0} \cdot \omega^{\frac{1}{\delta}} \cdot ||f||_h \tag{10}$$

holds for all x in a cube E provided that (a)E has side b and $b \ge b_0$, $(b)0 < \delta \le \delta_0$ and (c) every subcube of E of side δ contains a point of X. Here, $l(\lambda, n)$ is defined in (8), α_n denotes the volume of the unit ball in R^n , and c, Δ_0 are as in (9).

The number δ_0 and ω can be expressed specifically as

$$\delta_0 = \frac{1}{3C\gamma_n(m+1)}, \quad \omega = \left(\frac{2}{3}\right)^{\frac{1}{3C\gamma_n}}$$

where

$$C = \max\left\{2\rho'\sqrt{n}e^{2n\gamma_n}, \ \frac{2}{3b_0}\right\}, \quad \rho' = \frac{\rho}{c}.$$

The number ρ can be found in the remark following Lemma 2.1, γ_n is defined in Lemma 1.1, and $m = 1 + \frac{\lambda}{2}$ is defined in (4).

Proof. First, let ρ , γ_n , and b_0 be the constants appearing in Lemma 2.1, Lemma 1.1, and Theorem 2.4, repectively. Let

$$B = 2\rho'\sqrt{n}e^{2n\gamma_n}$$
 and $C = max\left\{B, \frac{2}{3b_0}\right\}$

where $\rho' = \frac{\rho}{c}$. Let

$$\delta_0 = \frac{1}{3C\gamma_n(m+1)},$$

where m is the order of c.p.d. of h.

Now, let x be any point of the cube E and recall that Theorem 4.2 of [13] implies that

$$|f(x) - s(x)| \le c_k ||f||_h \int_{\mathbb{R}^n} |y - x|^k d|\sigma|(y)$$
 (11)

whenever k > m, where σ is any measure supported on X such that

$$\int_{\mathbb{R}^n} p(y)d\sigma(y) = p(x) \tag{12}$$

for all polynomials p in P_{k-1} . Here

$$c_k = \left\{ \int_{R^n} \frac{|\xi|^{2k}}{(k!)^2} d\mu(\xi) \right\}^{1/2}$$

whenever k > m. By (9), for all $2k \ge 2m + 2$,

$$c_{k} = \left\{ \int_{R^{n}} \frac{|\xi|^{2k}}{(k!)^{2}} d\mu(\xi) \right\}^{1/2}$$

$$\leq \frac{1}{k!} \cdot \sqrt{l(\lambda, n)} \cdot (\frac{\pi}{2})^{1/4} \cdot \sqrt{n\alpha_{n}} \cdot c^{-k + \frac{\lambda}{2}} \cdot \sqrt{\Delta_{0}} \cdot \rho^{k} \cdot \sqrt{(2k)!}$$

$$\leq \sqrt{l(\lambda, n)} \cdot (\frac{\pi}{2})^{1/4} \cdot \sqrt{n\alpha_{n}} \cdot c^{\frac{\lambda}{2}} \cdot c^{-k} \cdot \sqrt{\Delta_{0}} \cdot (2\rho)^{k}$$
(13)

due to Lemma 2.3.

To obtain the desired bound on |f(x) - s(x)|, it suffices to find a suitable bound for

 $I = c_k \int_{\mathbb{R}^n} |y - x|^k d|\sigma|(y).$

This is done by choosing the measure σ appropriately. We proceed as follows: Let δ be a parameter as in the statement of the theorem. Since $\delta \leq \delta_0$ and $0 < 3C\gamma_n\delta \leq \frac{1}{m+1}$, we may choose an integer $k \geq m+1$ so that

$$1 \le 3C\gamma_n k\delta \le 2.$$

Note that $\gamma_n k\delta \leq b_0$ for such a k. Let Q be any cube which contains x, has side $\gamma_n k\delta$, and is contained in E. Subdivide Q into $(\gamma_n k)^n$ congruent subcubes of side δ . Since each of these subcubes must contain a point of X, select a point of X from each such subcube and call the resulting discrete set Y. By virtue of Lemma 2.2 we may conclude that there is a measure σ supported on Y which satisfies (12) and enjoys the estimate

$$\int_{\mathbb{R}^n} d|\sigma|(y) \le e^{2n\gamma_n k}.\tag{14}$$

We use this measure in (11) to obtain an estimate on I.

Using (13), (14), and the fact that support of σ is contained in Q whose diameter is $\sqrt{n}\gamma_n k\delta$, we may write

$$I \leq \sqrt{l(\lambda, n)} \cdot (\frac{\pi}{2})^{1/4} \cdot \sqrt{n\alpha_n} \cdot c^{\frac{\lambda}{2}} \cdot c^{-k} \cdot \sqrt{\Delta_0} \cdot (2\rho)^k \cdot (\sqrt{n\gamma_n k\delta})^k e^{2n\gamma_n k}$$

$$\leq (C\gamma_n k\delta)^k (\sqrt{l(\lambda, n)} \cdot (\frac{\pi}{2})^{1/4} \cdot \sqrt{n\alpha_n} \cdot c^{\frac{\lambda}{2}} \cdot \sqrt{\Delta_0}). \tag{15}$$

Since

$$C\gamma_n k\delta \le \frac{2}{3} \quad and \quad k \ge \frac{1}{3C\gamma_n\delta},$$

(15) implies that

$$I \leq \left\lceil \left(\frac{2}{3}\right)^{\frac{1}{3C\gamma_n}} \right\rceil^{\frac{1}{\delta}} \cdot \left(\sqrt{l(\lambda, n)} \cdot \left(\frac{\pi}{2}\right)^{1/4} \cdot \sqrt{n\alpha_n} \cdot c^{\frac{\lambda}{2}} \cdot \sqrt{\Delta_0}\right).$$

Hence we may conclude that

$$|f(x) - s(x)| \le \sqrt{l(\lambda, n)} \cdot \left(\frac{\pi}{2}\right)^{1/4} \cdot \sqrt{n\alpha_n} \cdot c^{\frac{\lambda}{2}} \cdot \sqrt{\Delta_0} \cdot \omega^{\frac{1}{\delta}} \cdot ||f||_h$$

where

$$\omega = \left(\frac{2}{3}\right)^{\frac{1}{3C\gamma_n}}.$$

This completes the proof.

What's noteworthy is that in Theorem 2.4 the parameter δ is not the generally used fill-distance. For easy use we should transform the theorem into a statement described by the fill-distance.

Let

$$d(\Omega, X) = \sup_{y \in \Omega} \inf_{x \in X} |y - x|$$

be the fill-distance. Observe that every cube of side δ contains a ball of radius $\frac{\delta}{2}$. Thus the subcube condition in Theorem2.4 is satisfied when $\delta = 2d(E, X)$. More generally, we can easily conclude the following:

Corollary 2.5 Suppose h is defined as in (4). Let μ be its corresponding measure as in (6). Then, given a positive number b_0 , there are positive constants d_0 and ω' , $0 < \omega' < 1$, which depend on b_0 for which the following is true: If $f \in \mathcal{C}_{h,m}$ and s is the h spline that interpolates f on a subset X of \mathbb{R}^n , then

$$|f(x) - s(x)| \le \sqrt{l(\lambda, n)} \cdot \left(\frac{\pi}{2}\right)^{\frac{1}{4}} \cdot \sqrt{n\alpha_n} \cdot c^{\frac{\lambda}{2}} \cdot \sqrt{\Delta_0} \cdot (\omega')^{\frac{1}{d}} \cdot ||f||_h \tag{16}$$

holds for all x in a cube $E \subseteq \Omega$, where Ω is a set which can be expressed as the union of rotations and translations of a fixed cube of side b_0 , provided that (a)E has side $b \ge b_0$, $(b)0 < d \le d_0$ and (c) every subcube of E of side 2d contains a point of X. Here, α_n denotes the volume of the unit ball in R^n and C, C0 are as in (9). Moreover C0 and C0 are C1 where C2 and C3 are C3 are C4.

Proof. Let $d_0 = \frac{\delta_0}{2}$ and $\delta = 2d$. Then $0 < d \le d_0$ iff $0 < \delta \le \delta_0$. Our corollary follows immediately by noting that $\omega^{\frac{1}{\delta}} = \omega^{\frac{1}{2d}} = \sqrt{\omega^{\frac{1}{d}}} = (\omega')^{\frac{1}{d}}$. \sharp

Remark: The space $C_{h,m}$ probably is unfamiliar to most people. It's introduced by Madych and Nelson in [12] and [13]. Later Luh made characterizations for it in [7] and [8]. Some people think that it's defined by Gelfand and Shilov's generalized Fourier transform, and is therefore difficult to deal with. This is not true. In fact, it can be characterized by Schwartz's generalized Fourier transform. The situation is not so bad. Moreover, some people think that $C_{h,m}$ is the closure of Wu and Schaback's function space which is defined in [17]. This is also not true. The two spaces have very little connection. Luh has also made a clarification for this problem. For further details, please see [9] and [10].

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